

# Parallel Iterative Reconstruction Tomography

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# Outline

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# Introduction and Background

- ▶ A fundamental mathematical tool in tomography is the Radon transform.
- ▶ For a compactly supported function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ , the Radon transform is defined by

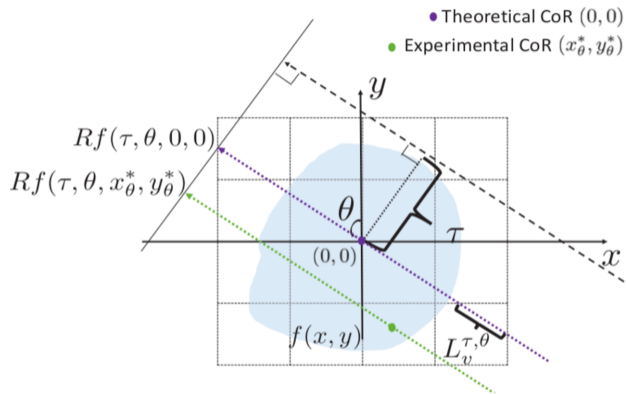
$$Rf(\tau, \theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \delta(\tau - x \cos \theta - y \sin \theta) dx dy$$

where  $\delta$  is the dirac delta function and the domain is restricted to  $\tau \in [0, \infty)$  and  $\theta \in [0, 2\pi)$ . It is assumed that  $f$  is well behaved.

- ▶ The Radon transform of a function is frequently called its sinogram.

# Introduction and Background

## Radon Transform



**Figure 1:** Geometric sketch of the Radon transform, which maps  $f$  from  $(x, y)$  space to  $(\theta, \tau)$  space. The purple line and the green line denote rotations of their previous position, as the  $y$ -axis, with respect to different CoRs, respectively.

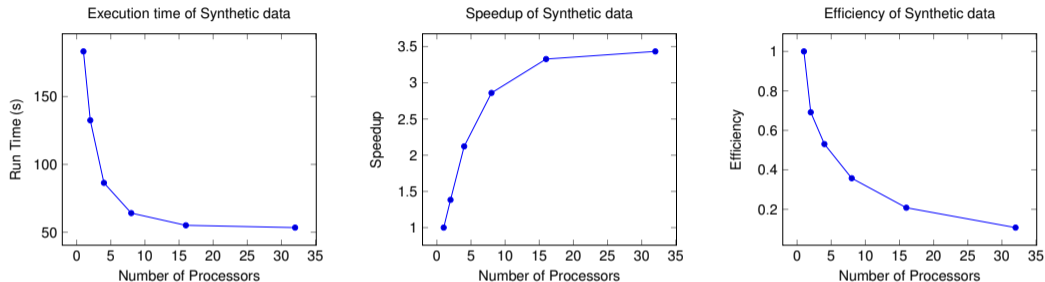
## Introduction and Background

- ▶ We implement an optimization-based reconstructive algorithm which estimates parameters and reconstructs the image concurrently.
- ▶ The code we developed interacts with PETSc/Tao.
- ▶ We calculate the function value and gradient through the use of FormFunctionGradient. To do this, we implement two methods
  - ▶ The first method is the standard reconstruction. The gradient is calculated without recovering the coordinates of the CoRs.
  - ▶ The second method is reconstruction with error correction. This method uses an implicit approach to recover the coordinates of the CoRs for  $(x_{\theta}^*, y_{\theta}^*)$ . A normalized Gaussian filter is used to dampen high-order Fourier coefficients.
- ▶ Variable bounds are set through TaoSetVariableBounds.
- ▶ The optimization problem is then solved through TaoSolve.

# Parallelization

- ▶ We measure the total execution time of reconstructing the Shepp–Logan phantom image with 1, 2, 4, 8, 16, and 32 processors.
- ▶ The head phantom image is created through `phantom(1000)` in Matlab. The image data is saved to a file with 497581 lines.
- ▶ The number of angles ( $N_\theta$ ) is set to 100 while the number of beam positions ( $N_r$ ) is set to 1415.
- ▶ We analyze the results to calculate speedup and parallel efficiency.

# Parallelization



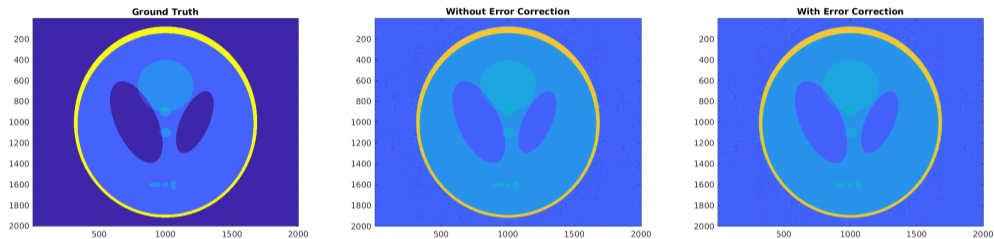
**Figure 2: Left:** Execution time for the Synthetic data set as a function of the number of processors. **Middle:** Performance of a parallel implementation - Speedup as a function of the number of processors. **Right:** Performance of a parallel implementation - Efficiency as a function of the number of processors.

# Results

- ▶ We create a high resolution image of the the Shepp–Logan phantom image by phantom(2000) in Matlab. The image data is saved to a file with 1992337 lines.
- ▶ The number of angles ( $N_\theta$ ) is set to 1000 and the number of beam positions ( $N_\tau$ ) is set to 2829. The number of processors is set to 32.
- ▶ Analysis is performed through reconstructing the image with and without error correction.



# Results



**Figure 3:** **Left:** Ground truth of the Shepp–Logan phantom image created by `phantom(2000)` in Matlab. **Middle:** The reconstructed Shepp–Logan phantom image without error correction. **Right:** The reconstructed Shepp–Logan phantom image with error correction.

## Future Work

- ▶ Investigate PIRT functionality with and without error correction on more data sets.
- ▶ Analyze the existing code for further performance improvements (replace VecSetValue with VecSetValues and make other improvements).
- ▶ Decide which Tao solver is best for use with PIRT.
- ▶ Investigate theoretical results after our reconstructive algorithm has been fully optimized.